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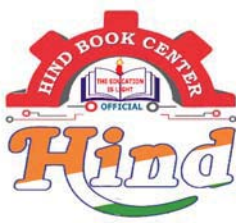
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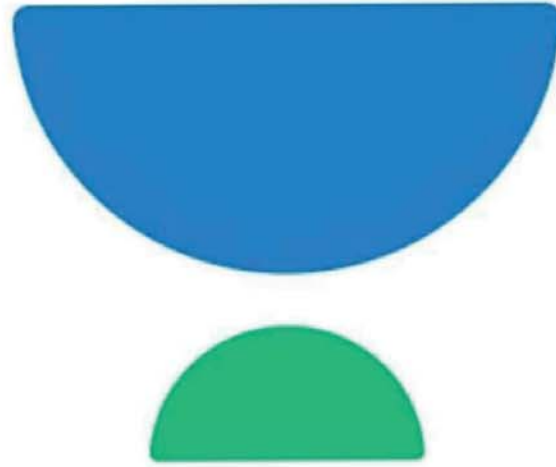
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Jaspal Sir's
Structure Analysis
Handwritten Notes

Written
By
Roopali Rai

Lesson 1 Feb 16

Structural Analysis

- structure can be defined as body of connected parts that is designed to carry loads even it is not intended to be occupied by us.

For eg: Bridges, dams, Railways, Retaining wall, tunnel, canals etc.

- The aim of structural analysis is to find force / moments in various components / parts of the structure.

- For the structure to remain in equilibrium, net forces (force & moments) acting on it must be zero in all directions.

Note: \Rightarrow If net force acting on body is zero & that body is at rest then it is termed to be in static equilibrium.

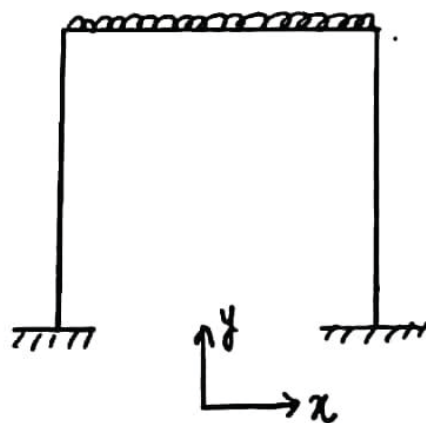
For eg: \Rightarrow Aircraft flying, train running, vessel sailing, car moving with const speed: Equilibrium.

But, Bridge, Dam, canal, retaining wall: static Equilibrium

- In a 2D structure or planar structure (in which all the members & forces are in one plane only), the equations of equilibrium are

$$\left. \begin{aligned} \sum F_x &= 0 \\ \sum F_y &= 0 \\ \sum M_z &= 0 \end{aligned} \right\} \text{3no's}$$

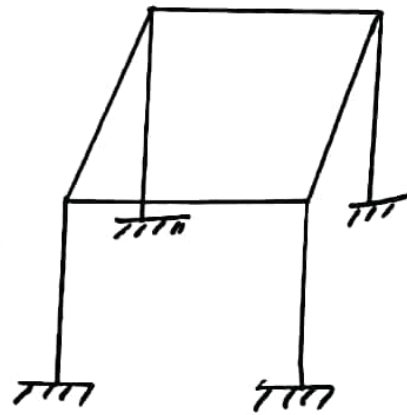
The above structure is assumed to be in x - y plane.



written by Roopali

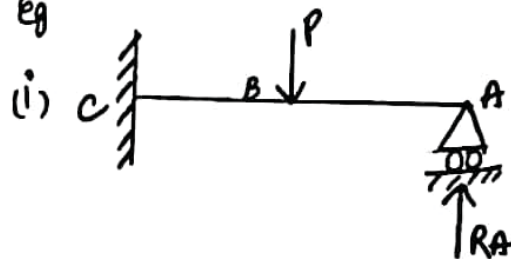
- In 3D structure or space structure (In which members & forces are in ~~3D~~ not in single plane) or are in 3D, the equations of equilibrium are:-

$$\left. \begin{aligned} \sum F_x &= 0 \\ \sum F_y &= 0 \\ \sum F_z &= 0 \\ \sum M_x &= 0 \\ \sum M_y &= 0 \\ \sum M_z &= 0 \end{aligned} \right\} 6 \text{ no.'s}$$



- In the analysis of structure can't be done just by using equations of equilibrium, then compatibility & energy equations are used.

Eq



$$\delta_A = 0$$

$$\downarrow \delta_{\text{load } P} - \uparrow \delta_{RA} = 0$$

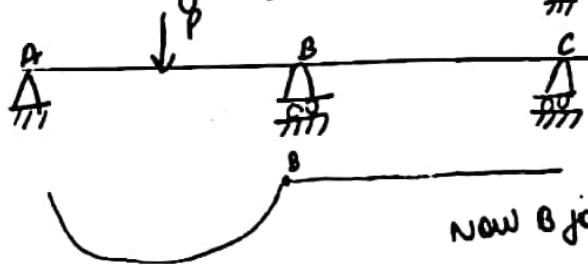
(ii)



$$\Delta_{AB} = 0$$

$$\Delta_{\text{Temp}} - \Delta_R = 0$$

- Here compatibility may be termed as continuity or good fit of material or structure or member or joint while being deformed under loading.



Compatibility eqⁿ not satisfy because support cannot be lifted.

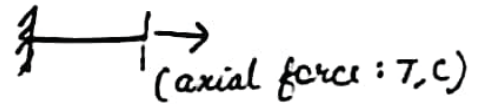
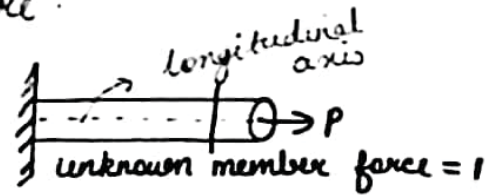
now B joint is not continuous.

• It is not compatible due to lifting of joint C

Types of Members Forming structure.

A) Axial member

- It is the simplest structural member
- for eg. bar or rod
- An axial member is a long straight body on which the forces are being applied along the longitudinal axis.
- An axial member can support axial force. (both tensile or compressive)



B) Beam / Frame Member

- It is a line element / member (element whose one dimension (length) is comparatively more than other two dimension (width, depth)) which is designed to resist SF & BM due to transverse load / moment.

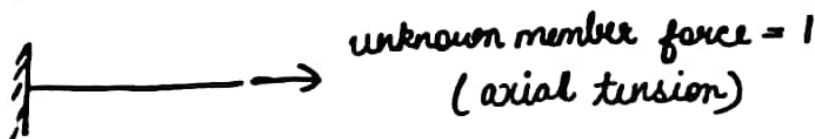
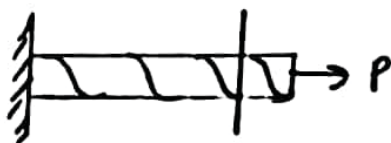
Note: → Transverse load is that load which is applied normal (\perp) to the longitudinal axis.



unknown member force = 3
(axial force, SF, BM).

C) Cable

- It is made of rope, chain or wire that serves different functions (according to the application)
- A cable can support axial force only, nature of which is tensile.



Lesson 2 Feb 17.

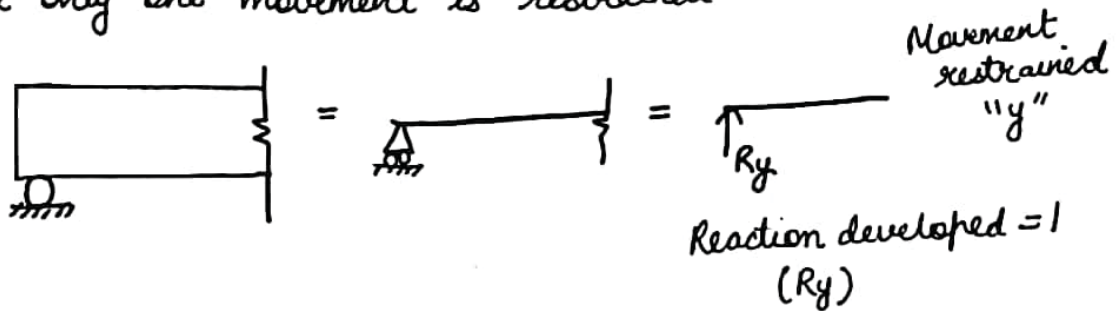
Types of support

- It is the boundary arrangement that can restrain movement of any point of the structure
- Due to the restraint of the movement, reactions are developed at the support in the direction opposite to the expected movement.

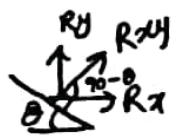
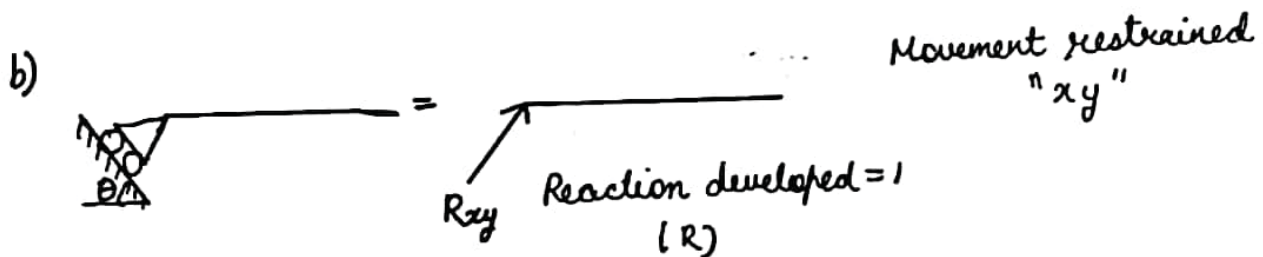
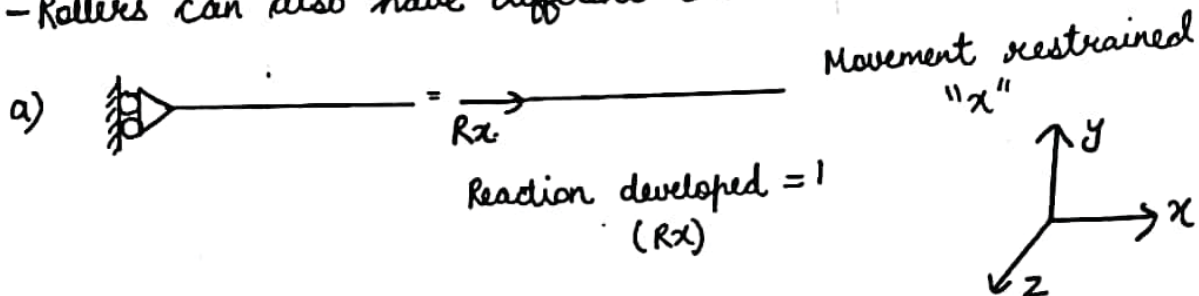
- Supports are generally of following types :-

A) Roller / Simple / Rocker support.

- It is the simplest support that gives only one reaction because only one movement is restrained.



- Rollers can also have different orientations as :-

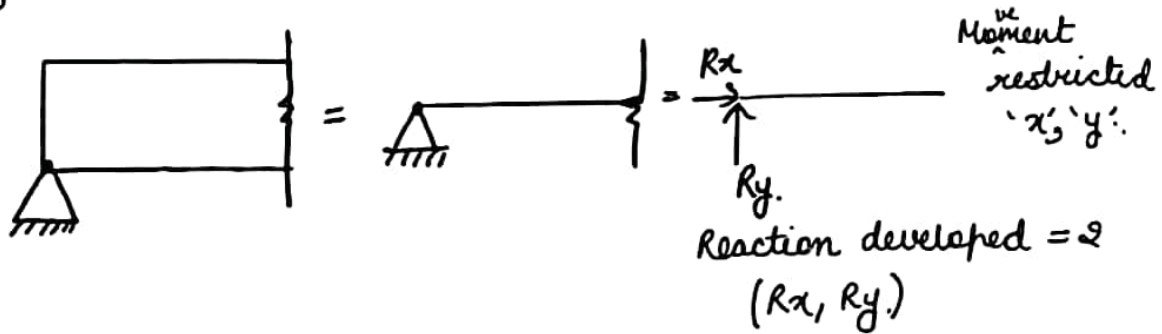


$$R_x = R_{xy} \sin \theta$$

$$R_y = R_{xy} \cos \theta$$

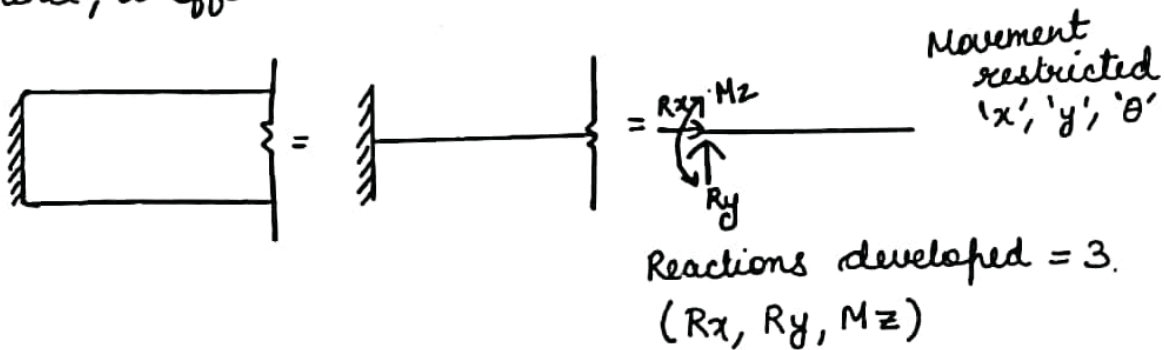
B) Hinged / Pinned support

- A pin/hinge gives resistance against two movement, hence offers two reactions



C) Fixed support

- It is the support that restrains complete movement of the point of structure.
- Hence, it offers three reactions



Note: Number of reactions in 3D or space structure

① $\downarrow \theta_z \quad \uparrow \theta_x \quad \rightarrow \theta_y$

No. of reactions
1 (R_y)

$\downarrow \theta_z \quad \uparrow \theta_x \quad \rightarrow \theta_y$

3 (R_x, R_y, R_z)

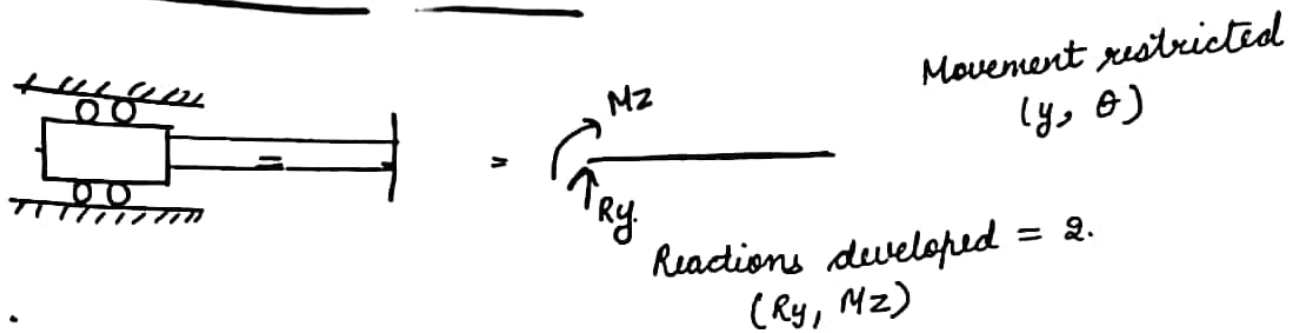


6 ($R_x, R_y, R_z, M_x, M_y, M_z$)

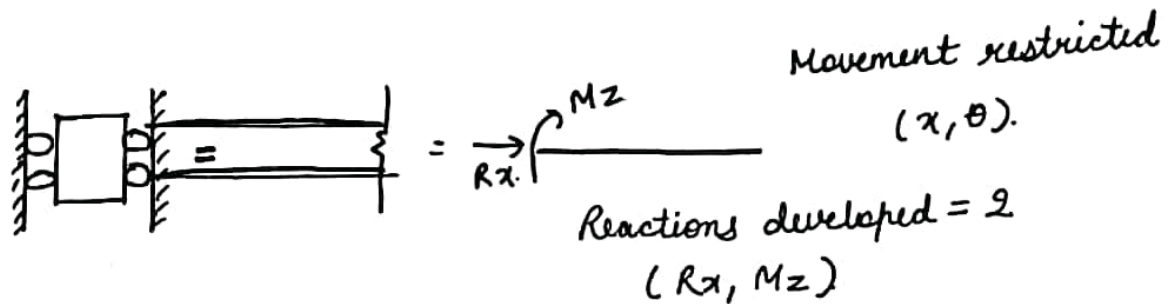
- ② Inclined roller support & hinge support both restrict the movement in x & y direction but inclined roller support offers 1 reaction (as θ is known) & hinged support offers 2 reaction (as θ is unknown)

d) Guided Roller Support.

- It is the type of roller support, movement of which is guided / restrained in a particular direction, hence it offers 1 additional reaction



or



e) Link support

- It is the type of support in which reactions is developed in the direction of cable or link

